

340129 - REAU-K5007 - Automatic Regulation

Coordinating unit:	340 - EPSEVG - Vilanova i la Geltrú School of Engineering
Teaching unit:	707 - ESAII - Department of Automatic Control
Academic year:	2019
Degree:	BACHELOR'S DEGREE IN INDUSTRIAL ELECTRONICS AND AUTOMATIC CONTROL ENGINEERING (Syllabus 2009). (Teaching unit Compulsory) BACHELOR'S DEGREE IN MECHANICAL ENGINEERING (Syllabus 2009). (Teaching unit Optional)
ECTS credits:	6
Teaching languages:	Catalan, Spanish

Teaching staff

Coordinator:	RAMON GUZMAN SOLA
Others:	FRANCISCO JAVIER RUIZ VEGAS RUBEN LUMBIARRES LÓPEZ RAMON GUZMAN SOLA

Prior skills

It is very convenient to have taken and passed the Fundamentals of Automatic course.

Degree competences to which the subject contributes

Specific:

1. CE25. Knowledge and ability of systems modeling and simulation.
2. CE26. Knowledge of automatic regulation and control techniques and its application into industrial automatization.
3. CE29. Ability to design automotion control systems.

Teaching methodology

Classroom training activities

- Participatory Lectures
- Conducting individual and team exercises
- Perform computer labs in
- Project Implementation Team
- Report writing and oral defense of problems, practices and projects

Educational activities outside the class:

- Perform exercises and theoretical or practical projects outside the classroom, individual and / or group.
- Review of theoretical concepts, study, work and individual and group analysis
- Tutoring and formative evaluation of the learning process

Learning objectives of the subject

The aim of this course is to provide basic knowledge of linear control systems description in discrete time in order to be able to design some discrete controllers.



340129 - REAU-K5007 - Automatic Regulation

Study load

Total learning time: 150h	Hours large group:	30h	20.00%
	Hours medium group:	0h	0.00%
	Hours small group:	30h	20.00%
	Guided activities:	0h	0.00%
	Self study:	90h	60.00%

340129 - REAU-K5007 - Automatic Regulation

Content

<p>Module 1: Introduction to control systems in discrete ti</p>	<p>Learning time: 18h Theory classes: 6h Self study : 12h</p>
<p>Description: Objective The aim of this first module is to introduce the basic architecture of digital control systems, applicability and benefits of their use.</p> <p>Subsections: * Types of signals * Digital control systems * DAC and ADC converters * Supervisor control vs direct digital control * Advantages of digital control vs analogic control</p>	
<p>Module 2: Mathematical models in discrete time</p>	<p>Learning time: 18h Theory classes: 6h Self study : 12h</p>
<p>Description: Objective The aim of this second module is to present the mathematical tools that are used to analyze control systems in discrete time. Will relate these techniques with the techniques used to analyze continuous systems.</p> <p>Content</p> <ul style="list-style-type: none"> * Z transform definition and properties * Methods of calculating the Z transform and its inverse 	
<p>Module 3: Signal sampling and reconstruction</p>	<p>Learning time: 18h Theory classes: 6h Self study : 12h</p>
<p>Description: Content: * Ideal sampling or impulse sampling * Sampled signal spectrum. Shannon Theorem. Ideal filter * 0 and 1 order holder * Star transform * Empiric rule</p>	

340129 - REAU-K5007 - Automatic Regulation

<p>Module 4: Discrete transform function</p>	<p>Learning time: 24h Theory classes: 8h Self study : 16h</p>
<p>Description: Content: * Equivalent discrete transform function * Blocs diagrams. Simplification</p>	
<p>Module 5: Time response and stability</p>	<p>Learning time: 18h Theory classes: 6h Self study : 12h</p>
<p>Description: Content: * Relation between s and z plains * Routh stability criterion (bilinear transform) * Jury stability criterion * steady state error in discrete systems</p>	
<p>Module 6: Discrete controllers design</p>	<p>Learning time: 42h Laboratory classes: 14h Self study : 28h</p>
<p>Description: Content: * Design of conventional controllers in s plane * Discretization of continuous controllers * Design of discrete controllers in z plane</p>	

340129 - REAU-K5007 - Automatic Regulation

Qualification system

There will be a first test (P) in the middle of the semester and a second test (F) at the end of the semester. The theory grade of the subject is calculated by the formula $T = \max(0.5 \cdot (P+F), F)$.

In the laboratory part, two exams are proposed: a mid term exam (LP) and a final exam (LF). The lab grade will be:
 $L = 0.5 \cdot LP + 0.5 \cdot LF$

The final grade is calculated as follows: $0.65 \cdot T + 0.35 \cdot L$

Re-assessment can be done by students with grades from 3 to 4.9. Re-assessment R substitute grade F and final grade is calculated as

$\min(5, 0.65 \cdot TR + 0.35 \cdot L)$, where:
 $TR = \max(R, (P+R)/2)$

Bibliography

Basic:

Ogata, Katsuhiko. Sistemas de control en tiempo discreto. 2a ed. México [etc.]: Prentice Hall Hispanoamericana, 1996. ISBN 9688805394.

Phillips, Charles L.; Nagle, H. Troy. Digital control system analysis and design. 3rd ed. Englewood Cliffs, N.J.: Prentice-Hall International, 1995. ISBN 013309832X.